

RS-LIDAR-16

16 beam LiDAR with Better Performance



RS-LiDAR-16, launched by RoboSense, is the first of its kind in China, world leading 16-beam miniature LiDAR product. Its main applications are in autonomous driving, robots environment perception, UAV mapping and etc.

The compact housing of the RS-LiDAR-16, mounted with 16 laser/detector pairs, rapidly spins and sends out high-frequency laser pulses to continuously scan the surrounding environment, collecting real-time 3D point clouds with reflectivity of objects to enable machines to "see" and providing reliable data for localization, navigation and obstacle avoidance.

Product Advantages



150m Measurement Range



2cm Range Accuracy



-30°C Cold-Resistant



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Sensor					
# of Lines	16	Horizontal FoV	360°		
Laser Wavelength	905nm	Vertical FoV	30°		
Laser Safety	Class 1 eye safe	Horizontal Resolution ²	0.1°/0.2°/0.4°		
Range ¹	150m (80m@10% NIST)	Vertical Resolution	2.0°		
Blind Spot	≤0.4m	Frame Rate	5Hz/10Hz/20Hz		
Range Accuracy (Typical) ³	Up to ±2cm	Rotation Speed	300/600/1200rpm(5/10/20Hz)		

Output				
Points Per Second	~300,000pts/s (Single Return Mode) ~600,000pts/s (Dual Return Mode)			
Ethernet Connection	100 Mbps			
Output	UDP packets over Ethernet			
UDP Packet include	Spatial Coordinates, Intensity, Timestamp, etc.			

Mechanical / Electrical / Operational				
Operating Voltage	9V – 32V	Dimension	ф109mm * H80.7 mm	
Power Consumption⁴	12W	Operating Temperature ⁵	–30°C ~ +60°C	
Weight(without cabling)	~0.87 kg	Storage Temperature	–40°C ~ +85°C	
Time Synchronization	\$GPRMC with 1PPS	Ingress Protection	IP67	

Applications











V2R

Robotics

Industrial

¹ The range performance is depending on circumstance factors, not only temperature, range and target reflectivity but also including other uncontrollable factors.

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2 The corresponding operating frequency of 0.1°/0.2°/0.4° is 5Hz/10Hz/20Hz.

3 The measurement target of accuracy is a 50% NIST diffuse reflectance target, the test performance is depending on circumstance factors, not only temperature, range and target reflectivity but also including other uncontrollable factors.

4 The power consumption is tested under 10Hz frame rate. The result is depending on circumstance factors, not only temperature, range and target reflectivity but also including other uncontrollable factors.

5 The operation temperature is depending on circumstance factors, not only sun load and air flow but also including other uncontrollable factors.