

Date:2005.10.26

Scanning Laser Range Finder URG-04LX

Specifications

| | | | | | |
|---------------|---|------------------|-------------|--|--------------|
| △ x 1 | Correction of errors | 3 | 2017.12.8 | Shibuva | RS-01023 |
| △ x 1 | Correction of errors | 4 | 2017.10.10 | Shibuva | RS-00995 |
| △ x 2 | Revision history of firmware added | 5 | 2008.4.25 | Yamamoto | PR-5451 |
| △ x 1 | Scanning area | 5 | 2007.4.16 | Maeda | PR-5269 |
| △ x 2 | Com. Protocol added, revision history of firmware added | 4,5 | 2007.1.18 | Maeda | PR-5225 |
| △ x 3 | Changes in resolution, revision history of firmware added | 3,5 | 2006.9.21 | Maeda | PR-5160 |
| △ x 5 | Changes in cable color | 4 | 2006.6.14 | Maeda | PR-5111 |
| Svmbol | Amended Reason | Pages | Date | Corrector | Amendment No |
| Approved by | Checked by | Drawn by | Designed by | <u>Scanning Laser Range Finder URG-04LX</u> Specifications | |
| <i>M.Hino</i> | <i>M.Maeda</i> | <i>M.Shibuya</i> | MAEDA | | |
| | | | | | 1/5 |

1. General

URG-04LX is a laser sensor for area scanning. The light source of the sensor is infrared laser of wavelength 785nm with laser class 1 safety. Scan area is 240° semicircle with maximum radius 4000mm. Pitch angle is 0.36° and sensor outputs the distance measured at every point (683 steps). Laser beam diameter is less than 20mm at 2000mm with maximum divergence 40mm at 4000mm.

Principle of distance measurement is based on calculation of the phase difference, due to which it is possible to obtain stable measurement with minimum influence from object's color and reflectance.

URG-04LX is designed under JISC8201-5-2 and IEC60947-5-2 standards for industrial applications.

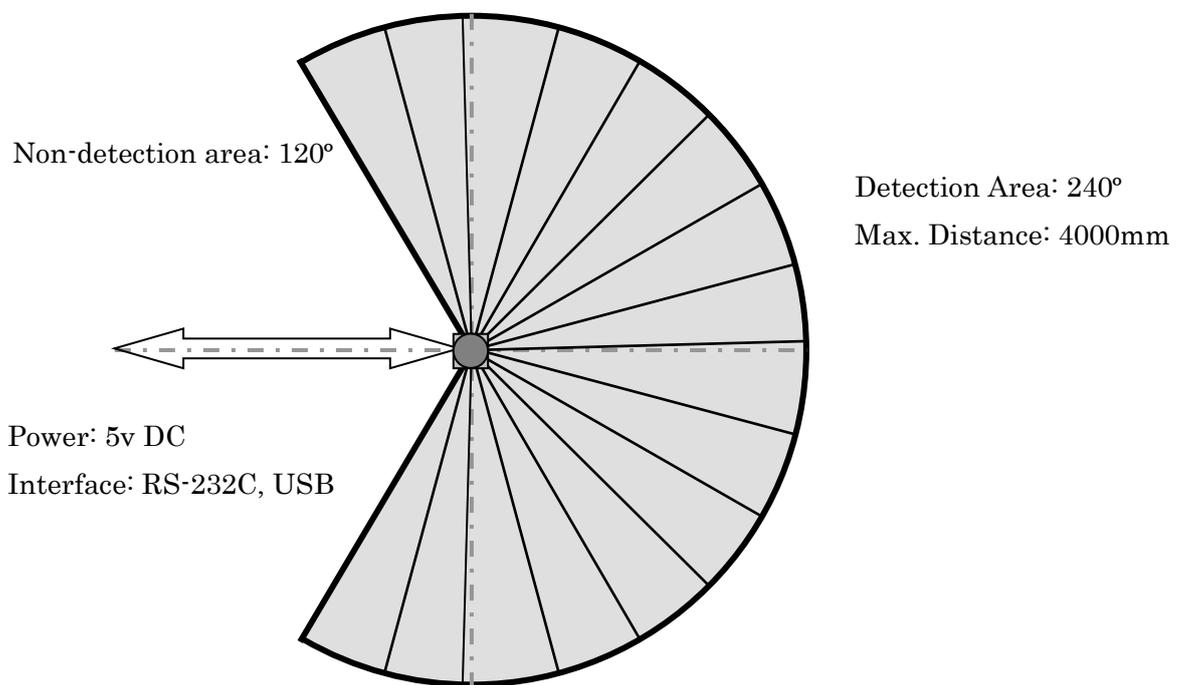


Figure 1

Note

Figure 1 shows the detectable area for white Kent sheet (70mm×70mm). Detection distance may vary with size and object.

2. Important Notice

This sensor is designed for indoor use only.

This sensor is not a safety device/tool

This sensor is not for use in military applications

Read specifications carefully before use.

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| Title | URG-04LX Specification | Drawing No | C-42-3389 | 2/5 |
|-------|------------------------|------------|-----------|-----|

3. Specifications

| | |
|--------------------------------|--|
| Product name | Scanning Laser Range Finder |
| Model | URG-04LX |
| Light source | Semiconductor laser diode ($\lambda=785\text{nm}$), Laser power : less than 0.8mW Laser safety Class 1 (IEC60825-1) |
| Power voltage | 5VDC $\pm 5\%$ |
| Power consumption | 500mA or less (Start-up current 800mA) |
| Detection | 60 mm ~ 4,095 mm (Guaranteed accuracy distance) 20mm ~ 5,600mm (Distance)* \triangle |
| Accuracy | Distance \triangle 20 ~ 60 ~ 1000mm: $\pm 10\text{mm}^* \triangle$ Distance 1000 ~ 4000mm: $\pm 1\%$ of measurement* \triangle |
| Resolution | 1 mm |
| Scan angle | 240° |
| Angular resolution | 0.36° (360° /1024) |
| Scanning speed | 100msec/scan |
| Interface | RS-232C (19.2, 57.6, 115.2 ,500 ,750 kbps) USB Version 2.0 FS mode (12Mbps) |
| Ambient (Temperature/Humidity) | -10 ~ 50°C / 85%RH or less (without dew and frost) |
| Storage temperature | -25 ~ 75°C |
| Ambient light resistance | 10000Lx or less |
| Vibration resistance | 1.5mm double amplitude, 10 ~ 55Hz, X, Y and Z direction (2 hours), 98m/s ² 55Hz ~ 150Hz in 2 minutes sweep, 1 hour each in X, Y and Z direction |
| Shock resistance | 196 m/s ² , 10 times each in X, Y and Z direction |
| Protective structure | Optics : IP64 Case : IP40 |
| Insulation | 10M Ω for DC 500Vmegger |
| Weight | Approx. 160 g |
| Casing | Polycarbonate |
| Dimension (W×D×H) | 50×50×70mm (Refer to design sheet No. C-40-3362) |

*Under standard test conditions with white Kent sheet 70mm×70mm

4. Quality reference value

| | |
|--------------------------------|--|
| Operating vibration resistance | 19.6m/s ² , 10Hz ~ 150Hz with 2 minutes sweep, 0.5 hours each in X, Y and Z direction |
| Operating impact resistance | 49 m/s ² , 10 times each in X, Y and Z direction |
| Angular speed | 360 deg/s |
| Angular acceleration | $\pi/2$ rad/s ² |
| Lifespan | 5 years (Vary on the operating conditions) |
| Noise level | 25db or less (at 300mm) |
| FDA | This product complies with 21 CFR parts 1040.10 and 1040.11. (Registration Number 0521258) |

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|-------|------------------------|------------|-----------|-----|
| Title | URG-04LX Specification | Drawing No | C-42-3389 | 3/5 |
|-------|------------------------|------------|-----------|-----|

5. Interface

- CN1 (8 Pins)

| | URG-04LX | Lead Color |
|---|----------------------|--|
| 1 | N.C. | RED  |
| 2 | N.C. | WHITE  |
| 3 | OUTPUT (SYNCHRONOUS) | BLACK |
| 4 | GND (9pin Dsub 5p) | PURPLE  |
| 5 | RxD (9pin Dsub 3p) | YELLOW  |
| 6 | TxD (9pin Dsub 2p) | GREEN  |
| 7 | 0V | BLUE |
| 8 | DC 5V | BROWN |

Note

GND and 0V are internally connected

A standard unit consists of power supply cable and 9-pin D-sub communication connector

- CN2 USB-mini (5 Pin)

Cable is not included. Use commercially available compatible unit.

- Communication protocol 

Please refer to the respective document for details on communication protocol

a) SCIP 1.0 : C-42-3320A 

b) SCIP 2.0 : C-42-3320B

- 1 Sync signal (approx. 12.5 ms) is outputted at each scan. Figure 2 shows the timing of the sync signal.

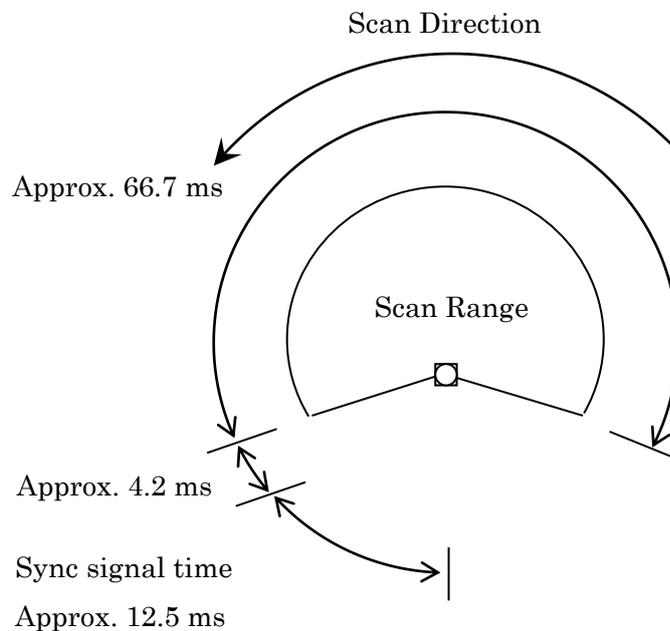


Figure 2

| Title | URG-04LX Specification | Drawing No | C-42-3389 | 4/5 |
|-------|------------------------|------------|-----------|-----|
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6. Output circuit:

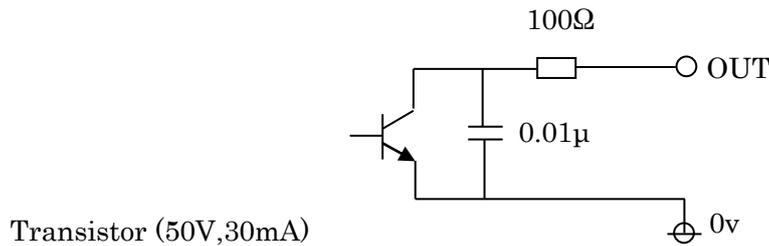


Figure 3

7. Additional notes:

- This sensor only needs 5VDC as power supply. Excessive power supply could cause damage to the sensor.
- Maximum data step is 683 steps. Since the angular resolution is 0.3515625° ($360^\circ / 1024$ steps), angular range is 239.765625° ($(683-1) \times 360 / 1024$).
- Angular resolution is configurable by the host. Read communication protocol specification (No C-42-3320) for details.
- Scan direction of the sensor is counterclockwise.
- In RS-232C communication, communication problems could happen if baud rate above 500 Kbps is set.
- USB driver used is the communication device class (CDC) supported by standard operating system. Sensor will be treated as COM port under the same utility when connected to the standard operating system.
- Plug and play function of the USB driver is not supported.

8. Firmware revision history

| Firmware version | Changes |
|---|---|
| Ver. 2.91a | Laser is not radiated and LED will continue to blink until the connection is established. |
| Ver. 3.1.00  | Fixed for SCIP 2.0. Function in ver. 2.91a is disabled. LED indicating the power supply will turn ON before communication is establish and start laser radiation. |
| Ver. 3.1.04  | Corrections on MD/MS of SCIP |
| Ver. 3.3.00  | HS command is added. Corrections on MD/MS of SCIP 2.0 Enhancement on error handling |

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|-------|------------------------|------------|-----------|-----|
| Title | URG-04LX Specification | Drawing No | C-42-3389 | 5/5 |
|-------|------------------------|------------|-----------|-----|